





Expression of interest

Contact details

Country	TURKEY
Name of the organisation	Istanbul Kültür University Technology Transfer Office
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Short description of the organisation

Provide a short description of the equipment available, the relations with the industry, the profile of the main researchers

Alparslan Güzey works in İstanbul Kültür University Technology Transfer Office as deputy director. He is PhD. Candidate of operational research In Istanbul University. PhD thesis about Concept of operations in urban air space and route optimization algorithms.

Within the scope of the EIT Urban Mobility BP 2021-2022 call period, the "Urban Air Traffic Management Development (UATMDEV)" project will be completed by the end of December, under the coordination of Istanbul Kultur University Technology Transfer Office. Project partners are given below:

Project partners:

- 1. Istanbul Kültür University,
- 2. ISBAK (Istanbul It and Smart City Technologies Inc.),
- 3. The Technical University of Catalonia (UPC),
- 4. Belgrade University Faculty of Traffic and Transport Engineering,
- 5. Fixar Aero Inc,
- 6. Belgrade City,
- 7. Ada Güzey Engineering,

Specific skills related to the project

Aspect 2:

Assessing and simulating the effects on multimodal network and traffic management of new forms of mobility (e.g. zero-emission, connected and automated vehicles and vessels, car sharing/pooling, active-/micro-mobility, sustainable land/air transport modes and drones), as well as of innovative services (e.g. Mobility/Logistics as a Service), in different urban and rural environments, considering the socio-economic acceptability and different user needs (including vulnerable and gender groups).

As urban air space concept of operation scenarios, UAVs will be tested in a simulation environment by trying different scenarios related to traffic management topics such as re-balancing/ re-scheduling/ route selection. It will be studied on how much the operational activities to be carried out in the urban







airspace will reduce land traffic and how much it will reduce carbon emissions. Real-time test flights will be conducted in the simulation environment according to SESAR CORUS Urban Air space regulations (U1, U2, U3, U4).

Proposed activities for the project

Indicate which activities you would like to implement during the project

It is aimed to optimize the route by assigning the tasks determined in the urban airspace to the existing drones. It is assumed that there are n missions, m drones and d skyports, and initially all drones will be located in the same port. Each task will be performed by a drone and a weight coefficient will be assigned to the tasks. The standby and flight time of each drone and the fuel consumed by each drone will form the total cost function. The effect of waiting times on the total cost function will be calculated by multiplying by the criticality coefficient of the task. The flight speed of the drone will also be calculated by the algorithm to minimize the total cost function. Thus, the algorithm will reduce the waiting time of missions with high criticality level, increase the flight speed of the drone, and keep the drone completes its mission, it will return to the central port. Multi-purpose optimization methods will be used for route optimization. The formula in which the amount of energy the drone will consume according to its flight speed is calculated will also be taken into account in the optimization algorithm. There will be 3 different scanarious; Static environment, dynamic environment(online routing) and collision avoidance system(CAS) test.

Project acronym / starting date	Main objectives	Main activities	Role in the project
UATMDEVDEM Jan 2022- Sep 2022	Air Traffic Management	Droneport, GSM Based Communication Device, UATM sub-systems.	Project Coordinator
TUBITAK 3005 Project	Application that creates historical routes with artificial intelligence routing algorithms	Field Study, route optimization, application development	Researcher
SmartAgriculturewithAutonomousGroundandAirVehicles:AnApplicationApplicationonHarvestOptimization			
OptimalEnergyConsumingonSprayinganAgriculturalFieldbyUsingMultipleUAVs			

References

Previous research project







Smart Agriculture		
with Autonomous		
Ground and Air		
Vehicles:		
Approaches to		
Calculating Optimal		
Number of Launch		
Location on to		
Harvest		
Optimization		