Challenges in Cyber-physical Systems

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Push: The technological enablers of CPS



From real-time and hybrid systems



The technological enablers of CPS



The third generation of control systems

- First generation: Analog Control
 - Technology: Feedback amplifiers
 - Theory: Frequency domain analysis Evans, Nyquist, Bode
- Second generation: Digital Control
 - Technology: Digital computers
 - Theory: State-space design
 - Real-Time Scheduling
- Third generation: Networked Control
 - Embedded computers
 - Wireless and wireline networks
 - Software
- Platform revolution

Foundation of system theory

- Linear systems
- Nonlinear systems
- Estimation
- Optimal control
- System identification
- Adaptive control
- Robust control
- Discrete event systems
- Hybrid systems

Bouquet of books



The technological enablers of CPS



From communicating to sensing to acting



Re-convergence of control, communication and computation



- "...the era of cyberspace and the Internet, with its emphasis on the computer as a communications device and as a vehicle for human interaction connects to a longer history of control systems that generated computers as networked communications devices."
 - D. Mindell in "Feedback, Control and Computing before Cybernetics," 2002
- ◆ 1950 2000 and continuing
 - Computation: ENIAC (1946), von Neumann (1944), Turing,...
 - Sensing and inference: Fisher, Wiener (1949),...
 - Actuation/Control: Bode, Kalman (1960),...
 - Communication: Shannon (1948), Nyquist,...
 - Signal Processing: FFT, Cooley-Tukey (1965),...



- 2000 onwards: Age of system building
 - Nodes that can communicate, control, compute
 - Larger grand re-unification of control, communication and computation
 - Pedagogical challenges: Knowledge of all these fields may be important
 - Undergraduate education? Graduate education?
 - Research challenges

The Pull: System building era of 21st century

- Satisfying greater demand for infrastructure and services with resource constraints
 - Transportation systems
 - Energy systems
 - Medical systems
 - Water systems
- Ongoing resource-aware system building era of the 21st century
- CPS with sensing, communication, computation, actuation needs to play a key role



The world's largest professional association for the advancement of technology

Centennial special issue

A special 13 May centennial issue will be published as the thirteenth issue of 2012, which will review 19 key technologies from three perspectives: the past, the present, and prospects for developments in the future. Technical topics include:

- 1. cyber-physical systems;
- 2. electric power and energy engineering;
- 3. engineering education;
- 4. entertainment technologies;
- 5. hjardware/software co-design;
- 6. mass storage and data retrieval;
- 7. materials for electronics, photonics & energy storage;
- 8. medical devices and electronics;
- 9. neurotechnological systems: the brain-computer interfact
- 10. optics and photonics;
- 11. personal and home electronics;
- 12. privacy and cybersecurity;
- 13. radio spectrum access;
- 14. the search for life: SETI;
- 15. science and engineering beyond Moore's Law;
- 16. social implications of technology;
- 17. space exploration and science;
- 18. transportation and navigation technology;
- 19. wireless communications technology.



PAPER

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May 2012: Special 13th issue

Cyber–Physical Systems: A Perspective at the Centennial

- 3 This paper surveys cyber-physical systems and the potential benefits of the
- 4 convergence of computing, communications, and control technologies
 - for developing next-generation engineered systems.
 - By KYOUNG-DAE KIM AND P. R. KUMAR, Fellow IEEE

Platform and system building revolution

- Mechanisms
 - How to implement?
- Policies
 - What to implement?
- Confluence
 - Hybrid
 - Discrete and continuous
 - Protocol and algorithm

What performance guarantees can be provided?

- How can we guarantee that systems will perform correctly and be safe?
- Ultimate goals: Correctness, safety, reliability

The importance of time

Real-time scheduling: (Liu and Layland `73)



N tasks

- Jobs of Task *n* arrive with period τ_n
- Deadline is end of period
- Worst case execution time c_n
- Rate monotone scheduling: Priority to smallest period task
- All deadlines met if $\sum_{n=1}^{N} \frac{c_n}{\tau_n} \le N(2^{1/N} 1) \quad (\rightarrow \ln 2 = 0.69 \text{ as } N \rightarrow \infty)$

What kind of guarantees can be provided over an unreliable medium like wireless?

In-Vehicle Networks



Wire harnesses are: Costly (>\$1000.00) Complex (>4,000 parts) Heavy (>40kg) Warranty issues (>65 IPTV)





Replace wires by an access point

Packets with deadlines

With I-Hong Hou





Packets with Deadlines

A Framework for Real-Time Wireless Networks

I-Hong Hou P.R. Kumar

Synthesis Lectures on Communication Networks

Jean Walrand, Series Edito

and Vivek Borkar

Provable Guarantees for Hybrid Systems

Autonomous ground traffic systems

Challenge of provable safety of algorithms for large systems

- Hybrid systems
 - Interaction between the continuous world of Newtonian dynamics and logical world of computers?
- How to integrate decisions made in continuous and discrete domains?
- Traditional hybrid systems is for *finite number of states*
 - Many models undecidable or doubly exponential complecity
- We need theories for infinite numbers of dynamic systems, each with uncountable numbers of states
- Combining distributed and centralized systems
 - How to augment distributed optimization with coordination rules that guarantee system-wide safety and liveness?

The architecture of the system and theoretical challenges



- How to go from finite time (MPC) to infinite time?
- How to handle dynamic oredrings?



20/24

Abstraction layers

EXPEDITED STATE UPDATE JOB PLACEMENT RULE CPU RESOURCE MANAGER

SERVICE

PROFILE

REGISTRY

SERVICE

SERVICE

NETWORK

MESSENGER

SERVICE

NETWORK

TIME

SERVICE

SCHEDULING SERVICE

INTERACTION FAULT TEMPORAL FAULT

DETECTOR SERVICEMANAGER SERVICE



Middleware manages the Components

(Baliga, Graham & K '04) (Graham, Baliga & K '09) (Kim & K '08) 21/24

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Collision avoidance



(Schuetz, Robinson & K '05)22/24

Provably correct behavior

Theorem

- Directed graph model of road network
 - Each bin has in-degree 1 or out-degree 1
 - System has no occupied cycles initially
- Road width: $W = R(1 \cos\beta(2\cos\alpha 1))$
 - Initial condition: $(d,\theta): d + R(1 \cos \theta) < W$
 - Intersection angles $\leq \gamma$, and road lengths: $L = (2\gamma R\underline{R})/(R \underline{R})$
 - Multiple cars with appropriate spacing
- Car control model: Kinematic model with turn radii \underline{R} and R
- Real time renewal tasks: HST scheduling with $\sum C_i / D_i \le 1$
- Then cars can be operated
 - Without collisions (Safety) or
 - Gridlocks (Deadlock)





(Baliga & K ' 05)

Thank you

